Introduction to Eigenspaces

Recall: Let A be a $n \times n$ matrix. Then a vector \boldsymbol{x} in \mathbb{R}^n is an *eigenvector* of A with corresponding *eigenvalue* λ (a scalar) if and only if

$$(A - \lambda I)\mathbf{x} = \mathbf{0}, \qquad \mathbf{x} \neq \mathbf{0}$$

Definition: Let A be a $n \times n$ matrix and let λ be an eigenvalue of A. The set E_{λ} defined

$$E_{\lambda} = \operatorname{null}(A - \lambda I) \tag{2}$$

(1)

is called the *eigenspace* of A corresponding to the eigenvalue λ .

Note 1: Since E_{λ} is the null space of $A - \lambda I$, the eigenspace E_{λ} is a subpsace of \mathbb{R}^{n} .

Note 2: E_{λ} contains the zero vector and <u>all</u> eigenvectors of A with eigenvalue λ .

Example: Consider the matrix $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$.

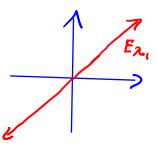
1. Find the eigenvalues of A.

 $O = det(A - \lambda I) = det(\begin{bmatrix} 1 - \lambda & 2 \\ 2 & 1 - \lambda \end{bmatrix})$ = $(1 - \lambda)^2 - 4 = \lambda^2 - 2\lambda - 3 = (\lambda - 3)(\lambda + 1)$ The eigenvalues of A are $\lambda_1 = 3, \lambda_2 = -1$. 2. One eigenvalue of $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ is $\lambda_1 = 3$. Find a basis for E_{λ_1} and calculate dim (E_{λ_1}) . Sketch the eigenspace E_{λ_1} .

$$E_{\mathcal{R}_{i}} = \operatorname{null}(A - \mathcal{R}_{i}I) = \operatorname{null}(A - 3I) = \operatorname{null}\left(\begin{bmatrix} -2 & 2\\ 2 & -2 \end{bmatrix}\right)$$

= null $\left(\begin{bmatrix} 1 & -1\\ 0 & 0 \end{bmatrix}\right) = \begin{cases} X_{i}\\ X_{2}\\ \vdots \end{cases}; X_{i} - X_{2} = \emptyset \end{cases}$
= $\begin{cases} t_{i}\\ t_{i}\\ \vdots \end{cases}; t in R = \begin{cases} t_{i}\\ t_{i}\\ \vdots \end{cases}; t in R = span(\begin{bmatrix} 1\\ 1 \end{bmatrix})$

 $B_{1} = \{ [i] \}$ dim $(E_{n}_{1}) = 1$



3. The other eigenvalue of $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ is $\lambda_2 = -1$. Find a basis for E_{λ_2} and calculate $\dim(E_{\lambda_2})$. Sketch the eigenspace E_{λ_2} .

 $E_{\lambda_{2}} = \operatorname{null}(A - \lambda_{2}I) = \operatorname{null}(A+I) = \operatorname{null}\left(\begin{bmatrix}2\\2\\2\end{bmatrix}\right)$ $= \operatorname{null}\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \left\{\begin{bmatrix}X_{1}\\X_{2}\end{bmatrix}: X_{1}+X_{2}=0\right\} = \left\{t\begin{bmatrix}1\\1\end{bmatrix}: t \text{ in } R\right\}$ $= \operatorname{span}\left(\begin{bmatrix}-1\\1\end{bmatrix}\right),$ $B_{2} = \left\{\begin{bmatrix}-1\\1\end{bmatrix}\right\} \quad \dim\left(E_{\lambda_{2}}\right) = 1$

Example: The matrix $A = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$ has eigenvalue $\lambda_1 = 1$. Find a basis for E_{λ_1} and calculate dim (E_{λ_1}) . Give a geometric description of the eigenspace E_{λ_1} .

$$\begin{split} & E_{\mathcal{R}_{i}} = \operatorname{null}\left(A - \mathcal{R}_{i} \mathcal{I}\right) = \operatorname{null}\left(\begin{bmatrix}1 & 1 & 1 \\ 1 & 1 & 1\end{bmatrix}\right) = \operatorname{null}\left(\begin{bmatrix}1 & 1 & 1 \\ 1 & 1 & 1\end{bmatrix}\right) \\ & = \left\{\begin{bmatrix}X_{i} \\ X_{2} \\ X_{3} \end{bmatrix} : X_{i} + X_{2} e X_{3} = 0\right\} = \left\{\begin{bmatrix}x_{i} & t_{i} \\ t_{i} \end{bmatrix} : t_{i} + t_{i} = \left\{\begin{bmatrix}x_{i} \\ t_{i} \end{bmatrix} : t_{i} + t_{i} \end{bmatrix} : t_{i} + t_{i} = \left\{\begin{bmatrix}x_{i} \\ t_{i} \end{bmatrix} : t_{i} + t_{i} \end{bmatrix} = \left\{\begin{bmatrix}x_{i} \\ t_{i} \end{bmatrix} : t_{i} + t_{i} \end{bmatrix} = \operatorname{span}\left(\begin{bmatrix}-1 \\ t_{i} \end{bmatrix}, \begin{bmatrix}-1 \\ t_{i} \end{bmatrix}\right) \\ & B_{i} = \left\{\begin{bmatrix}-1 \\ t_{i} \end{bmatrix}, \begin{bmatrix}-1 \\ t_{i} \end{bmatrix}\right\} = \operatorname{dim}(E_{\mathcal{R}_{i}}) = 2 \end{split}$$